

**NEC 304**

**STLD**

**Lecture 33**

***Arithmetic Logic Unit (ALU)***

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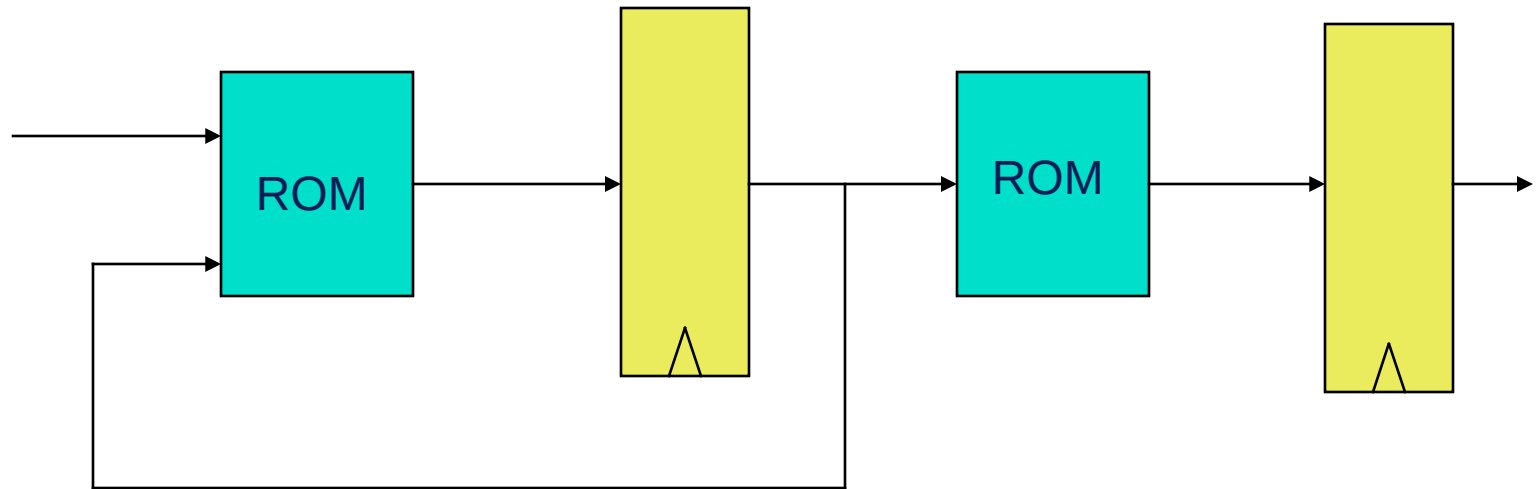
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# Overview

- Main computation unit in most computer systems
- ALUs perform a variety of different functions
  - Add, subtract, OR, AND...
- Example: ALU chip (74LS382)
  - Has data and control inputs
- Individual chips can be chained together to make larger ALUs
- ALUs are important parts of **datapaths**
  - ROMs often are used in the **control path**
- Build a data and control path

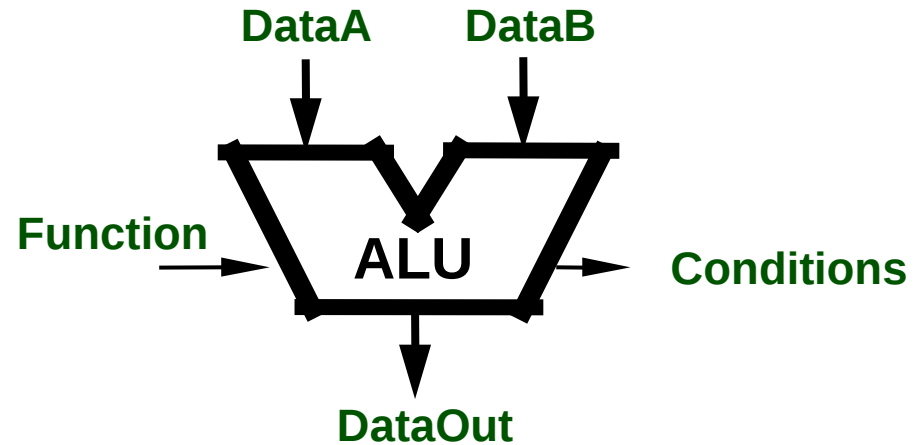
# ROM-based Moore Machine Timing

- What is the maximum clock frequency of this circuit?
- Does this circuit satisfy **hold time** constraints?

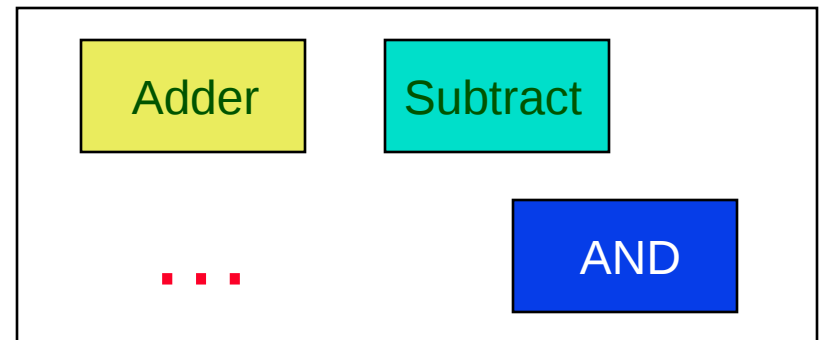


# Arithmetic Logic Unit

- Arithmetic logic unit functions
  - Two multi-bit data inputs
  - **Function** indicates action (e.g. add, subtract, OR...)
- **DataOut** is same bit width as multi-bit inputs (**DataA** and **DataB**)
- ALU is combinational
- **Conditions** indicate special conditions of arithmetic activity (e.g. overflow).

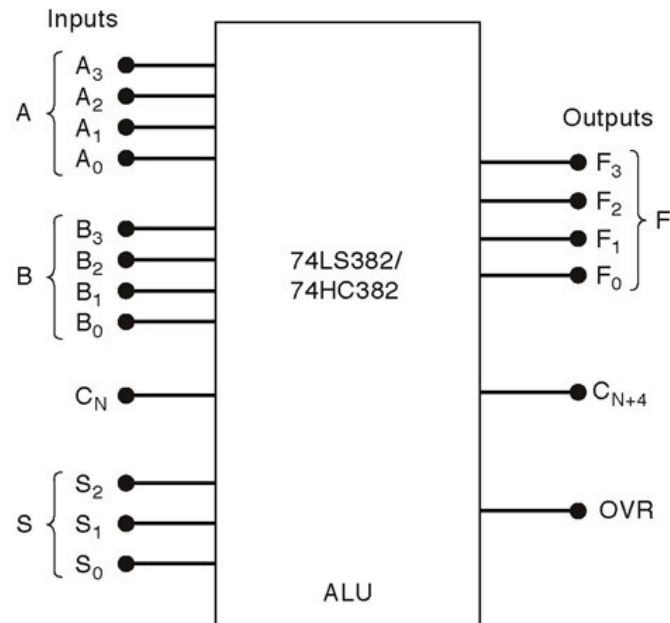


Think of ALU as a number of other arithmetic and logic blocks in a single box! **Function** selects the block



# ALU Integrated Circuit

- Integrated circuit – off-the-shelf components
- Examine the functionality of this ALU chip



A = 4-bit input number  
 B = 4-bit input number  
 C<sub>N</sub> = carry into LSB position  
 S = 3-bit operation select inputs  
 F = 4-bit output number  
 C<sub>N+4</sub> = carry out of MSB position  
 OVR = overflow indicator

(a)

Function Table

S <sub>2</sub>	S <sub>1</sub>	S <sub>0</sub>	Operation	Comments
0	0	0	CLEAR	F <sub>3</sub> F <sub>2</sub> F <sub>1</sub> F <sub>0</sub> = 0000
0	0	1	B minus A	Needs C <sub>N</sub> = 1
0	1	0	A minus B	
0	1	1	A plus B	Needs C <sub>N</sub> = 0
1	0	0	A ⊕ B	Exclusive-OR
1	0	1	A + B	OR
1	1	0	AB	AND
1	1	1	PRESET	F <sub>3</sub> F <sub>2</sub> F <sub>1</sub> F <sub>0</sub> = 1111

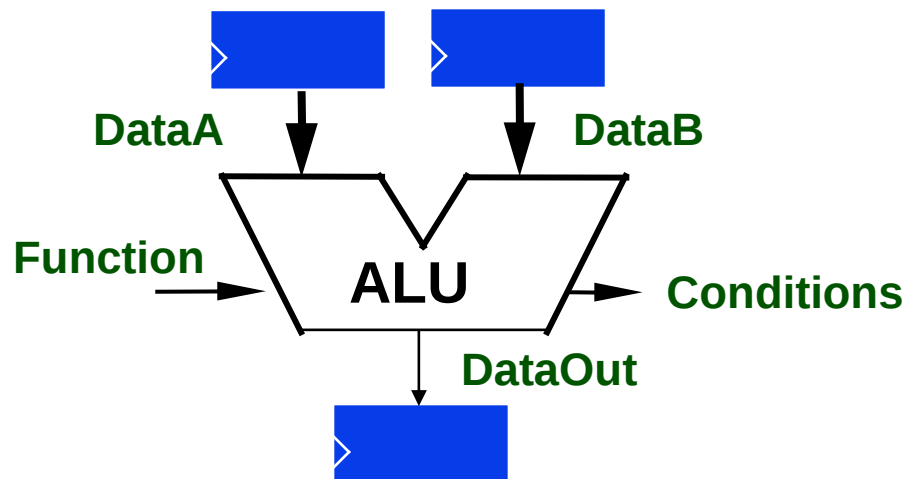
Notes: S inputs select operation.  
 OVR = 1 for signed-number overflow.

(b)

Performs 8 functions

## Example

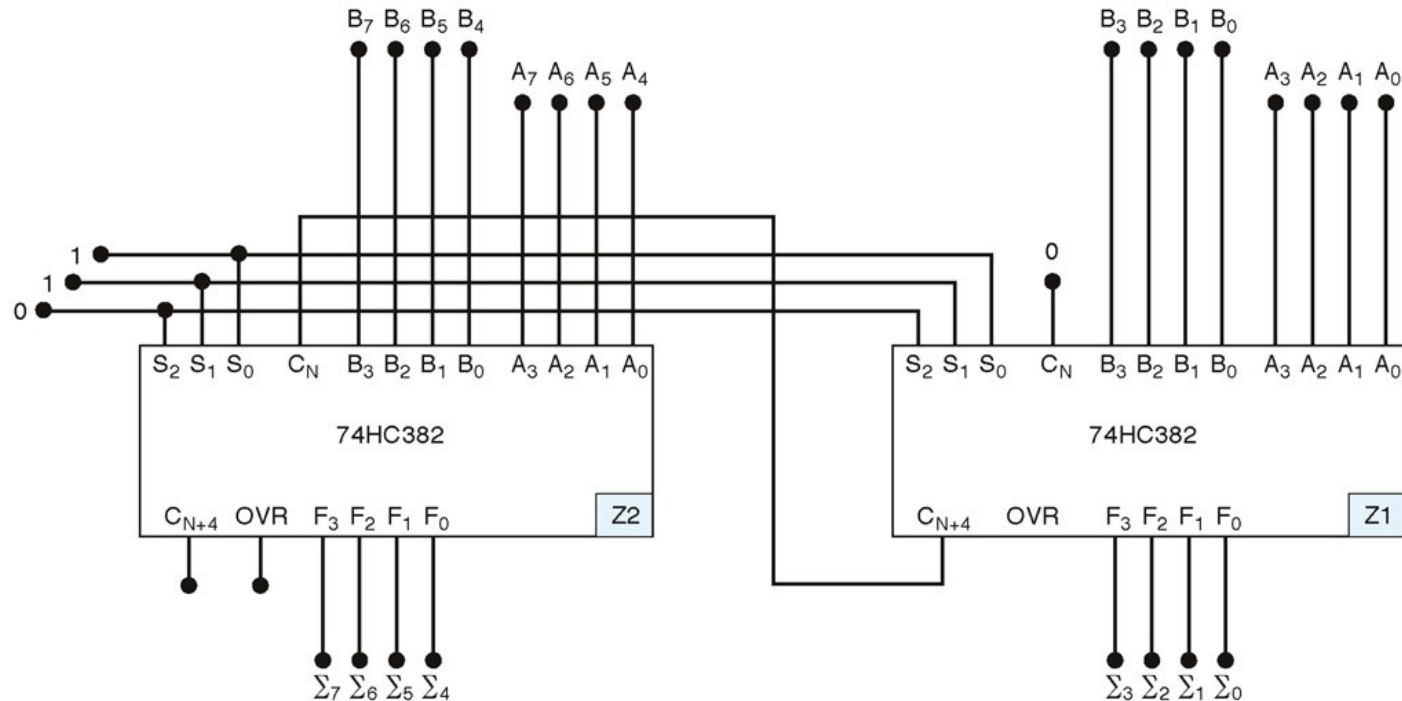
- Determine the 74HC382 ALU outputs for the following inputs:  $S_2S_1S_0=010$ ,  $A_3A_2A_1A_0=0100$ ,  $B_3B_2B_1B_0=0001$ , and  $C_N=1$ .
  - Function code indicates **subtract**
  - **$0100 - 0001 = 0011$**
- Change the select code to 101 and repeat.
  - Function code indicates **OR**
  - **$0100 \text{ OR } 0001 = 0101$**



Synchronize ALU  
with a clock

# Expanding the ALU

- Multi-bit ALU created by connecting carry output of low-order chip to carry in of high order

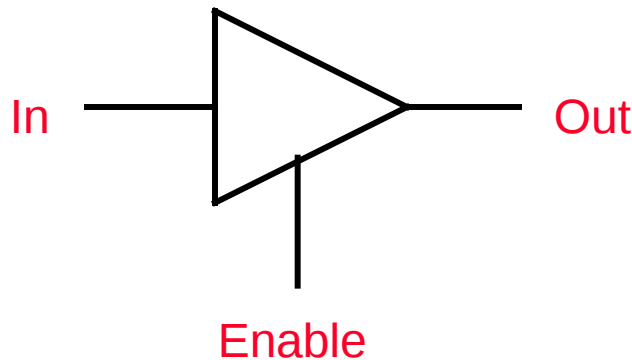


Notes: Z1 adds lower-order bits.  
Z2 adds higher-order bits.  
 $\Sigma_7 - \Sigma_0 = 8\text{-bit sum}$ .  
OVR of Z2 is 8-bit overflow indicator.

Eight-bit ALU formed from 2 four-bit ALUs

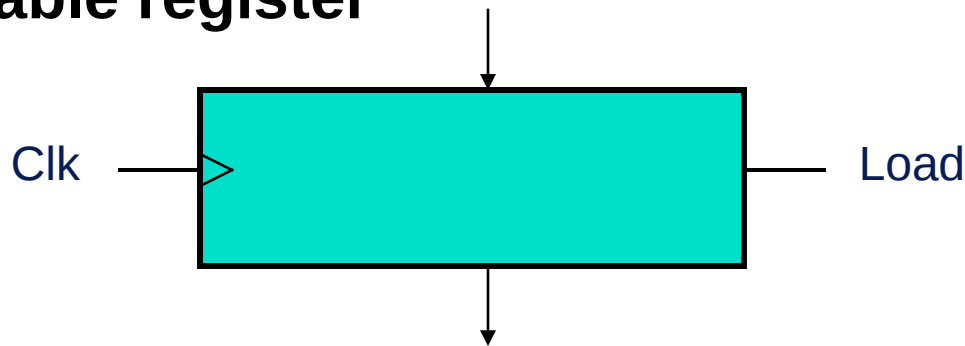
# Datapath components

## ° Tri-state buffer



If Enable asserted,  
Out = In  
Otherwise  
Out open-circuit

## ° Loadable register



Data stored on rising edge if Load is asserted (e.g. Load = 1)



# Computation in a Typical Computer

- Control logic often implemented as a finite state machine (including ROMs)
- Datapath contains blocks such as ALUs, registers, tri-state buffers, and RAMs
- In a processor chip often a 5 to 1 ratio of datapath to control logic

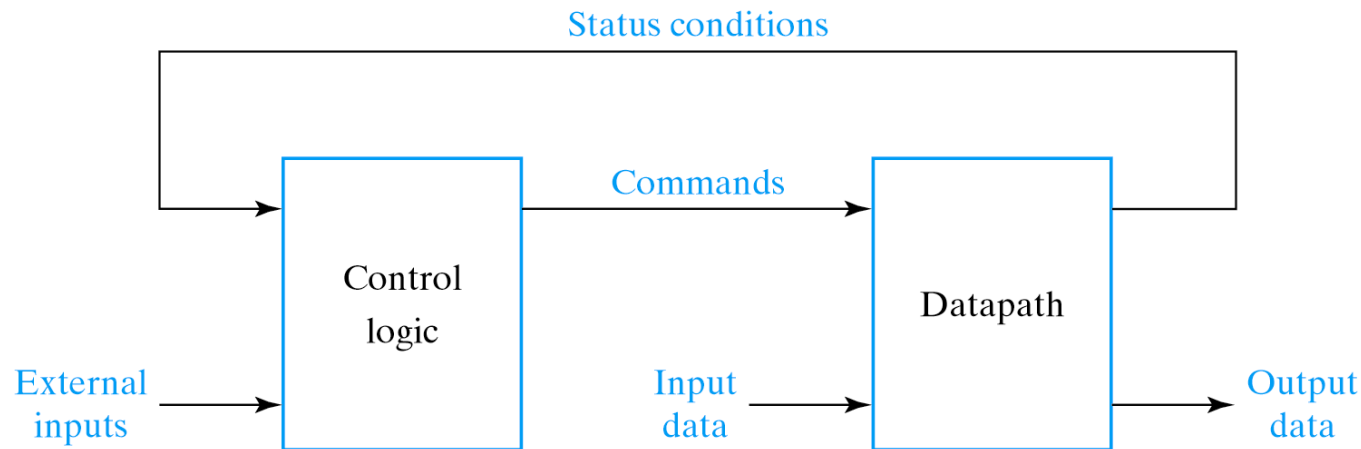


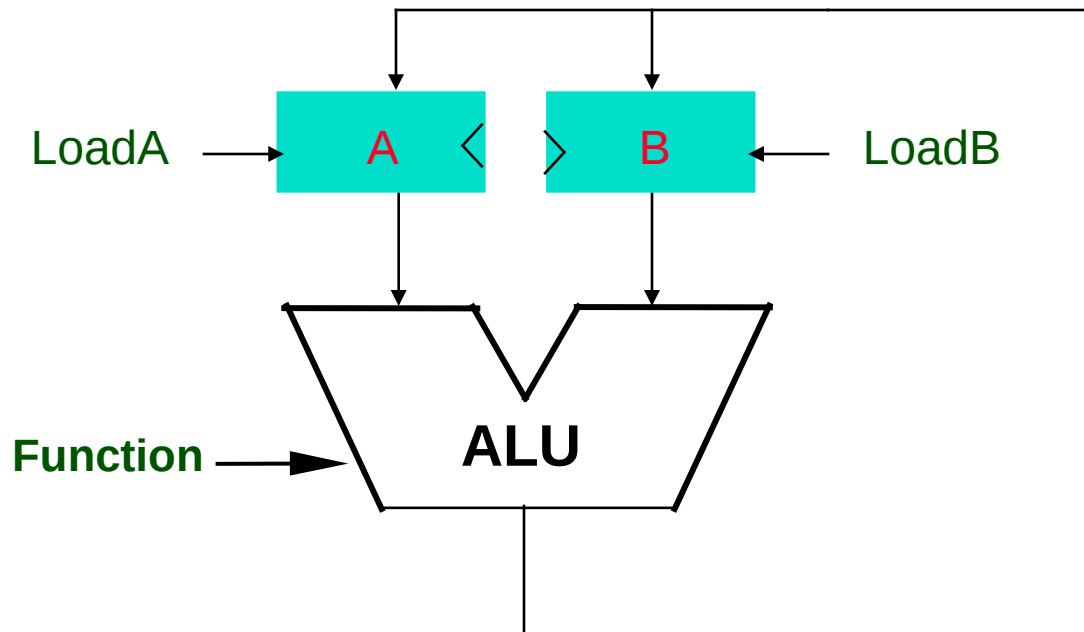
Fig. 8-2 Control and Datapath Interaction

# Using a Datapath

- Consider the following computation steps

1. ADD A, B and put result in A
2. Subtract A, B and put result in B
3. OR A, B put result in A
- Repeat starting from step 1

Determine values  
for Function, LoadA, LoadB



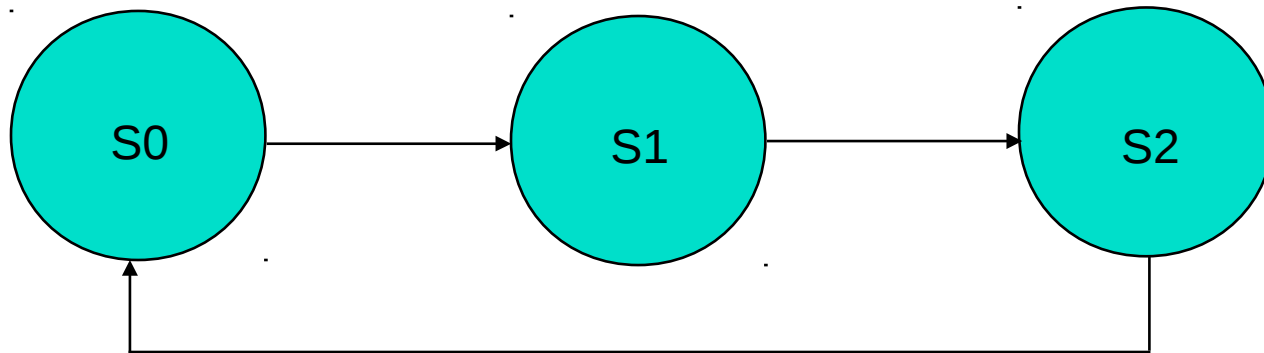
# Modeling Control as a State Machine

- Consider the following computation steps

1. ADD A, B and put result in A
  2. Subtract A, B and put result in B
  3. OR A, B put result in A
- Repeat starting from step 1

Determine values  
for Function, LoadA, LoadB

Model control as a state machine.  
Determine control outputs for each state



# Modeling Control as a State Machine

- Consider the following computation steps

1. ADD A, B and put result in A
  2. Subtract A, B and put result in B
  3. OR A, B put result in A
- Repeat starting from step 1

States

S0 = 00

S1 = 01

S2 = 10

Present State	Next State	Function	LoadA	LoadB
00	01	011	1	0
01	10	010	0	1
10	00	101	1	0

We know how to implement this using an SOP.  
Can we use a ROM?

# ROM Implementation of State Machine

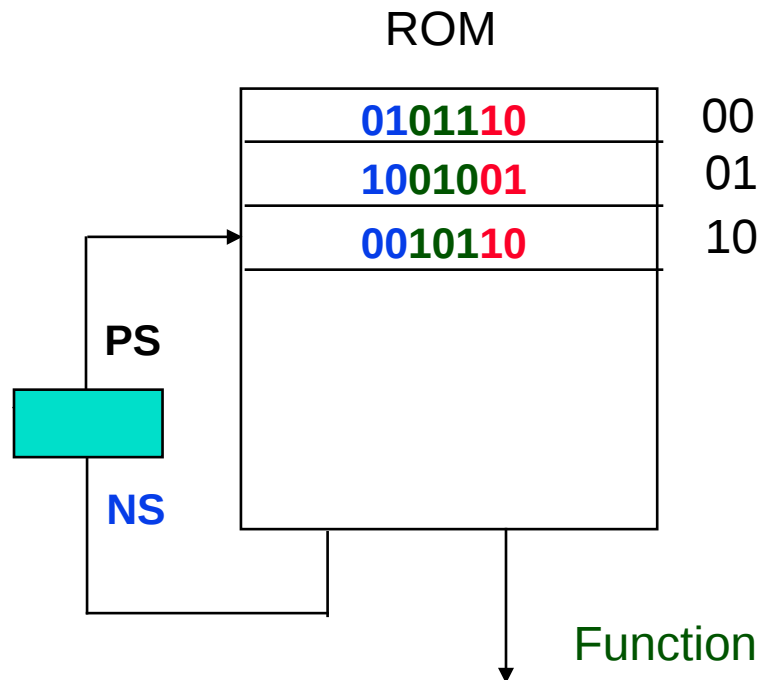
Present State	Next State	Function	LoadA	LoadB
00	01	011	1	0
01	10	010	0	1
10	00	101	1	0

States

S0 = 00

S1 = 01

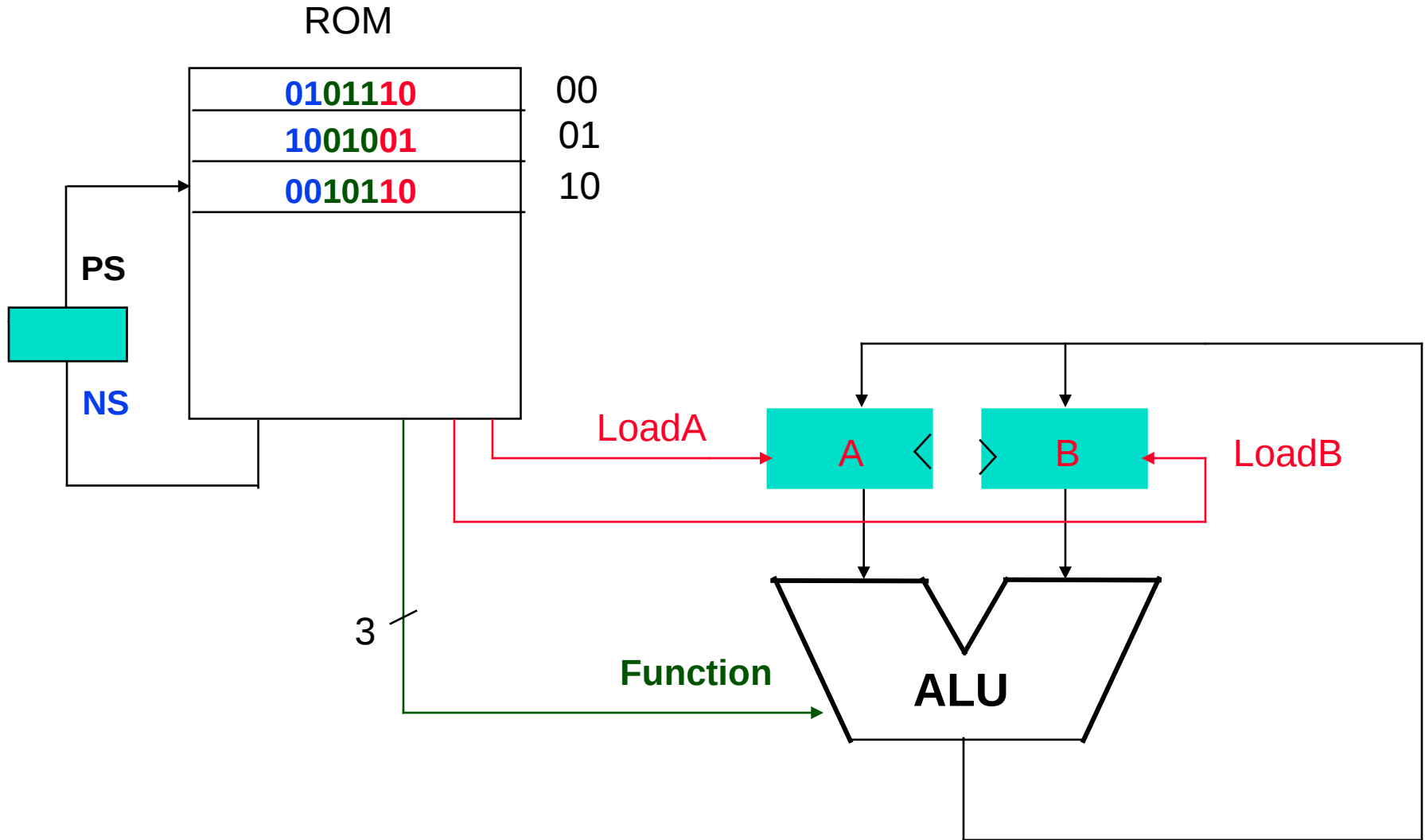
S2 = 10



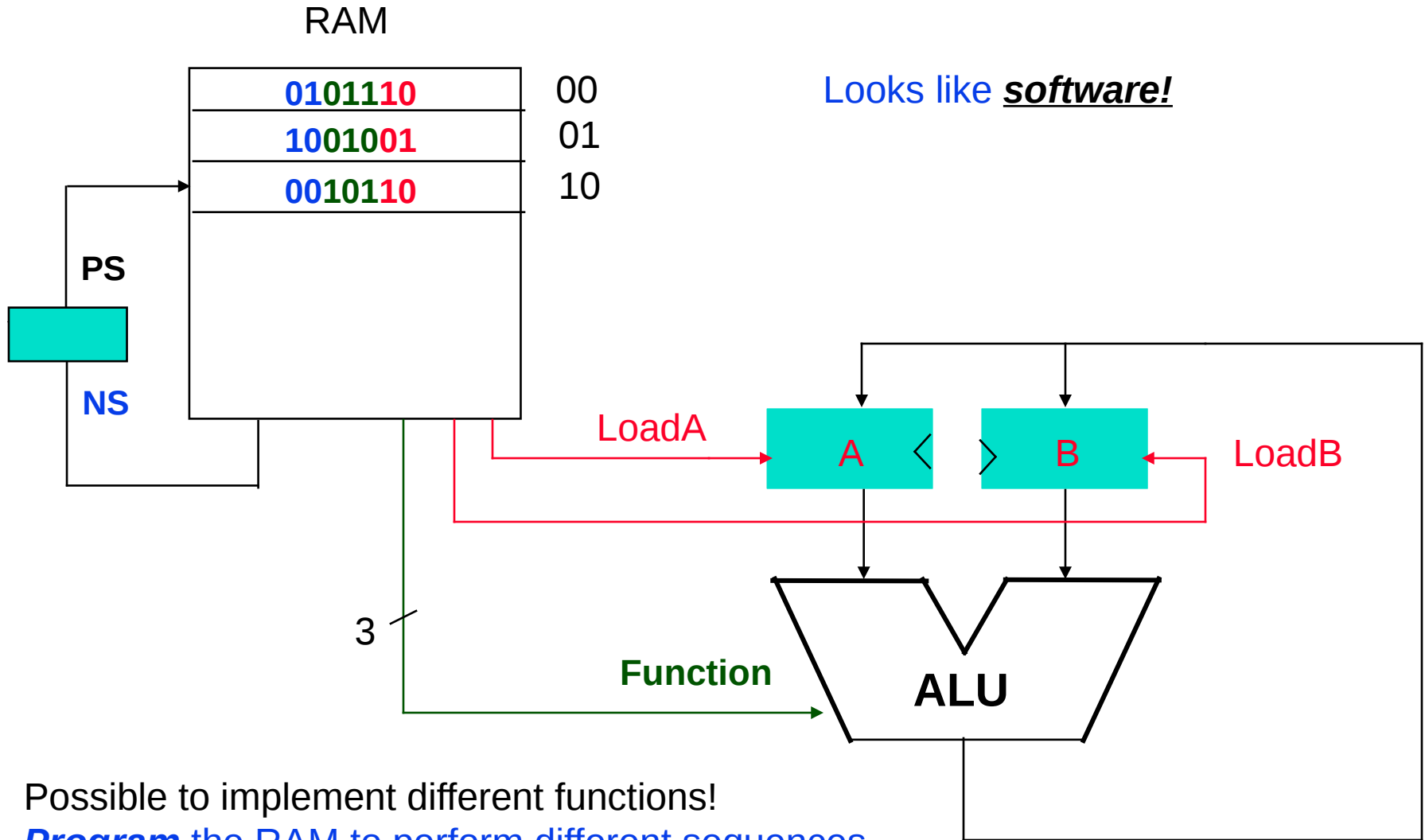
Note: No minimization!

One line in ROM for each state

# Putting the Control and Datapath Together



# What if we replaced the ROM with RAM?



Possible to implement different functions!

*Program* the RAM to perform different sequences

# Summary

- **ALU circuit can perform many functions**
  - **Combinational circuit**
- **ALU chips can be combined together to form larger ALU chips**
  - **Remember to connect carry out to carry in**
- **ALUs form the basis of datapaths**
- **ROMs can form the basis of control paths**
- **Combine the two together to build a computing circuit**
- **Next time: more data and control paths**